

## SWARNANDHRA COLLEGE OF ENGINEERING AND TECHNOLOGY

(Autonomous)

Narsapur, West Godavari District, A.P. 534280

## DEPARTMENT OF MECHANICAL ENGINEERING

## TEACHING PLAN

2 A 3 A 4 Es 5 Ai 6 Co	Discuss the Analyse velo Apply the ef Estimate unb	MES plane mo	acceleration o	2.000 Miles	6 legree of freedo	2024-25	16	-12-2024				
1 D 2 A 3 A 4 Es 5 A 6 C UNIT	Discuss the Analyse velo Apply the ef Estimate unb	plane mo	acceleration o	2.000 Miles	legree of freed							
2 A 3 A 4 Es 5 Ai 6 Co	Analyse velo Apply the ef Estimate unb	ocity and a	acceleration o	2.000 Miles	legree of freed							
3 A 4 Es 5 Ar 6 C	apply the ef	fects of gy	**************************************	0.1100	Discuss the plane motion mechanism with single degree of freedom. [K2]							
3 A 4 Es 5 Ai 6 Co	apply the ef	fects of gy	**************************************	Analyse velocity and acceleration of different links in a mechanism [K4]								
4 Es 5 At 6 Cd	stimate unb		mascanie con									
5 Ai 6 C	THE REAL PROPERTY.		Apply the effects of gyroscopic couple in ships, aeroplanes and road vehicles. [K3]									
6 C	inalyse free	stimate unbalance mass in rotating machines [K3]										
UNIT		yse free and forced vibrations of single degree freedom systems. [K4]										
UNIT	Construction	of turnin	g moment dia	grams and apply	them in designi	ng flywhee	ls. [K3	I				
	Out Comes / Bloom's Level	Topics No.		Topics/Activity		Text Book / Referen ce	Cont act Hour	Delivery Method				
		Unit-1 Simple Mechanisms										
	Examine the plane motion mechanism with single degree of freedom	1.1		on of mechanisms concepts and defir		T1, R1	2	Chalk and talk /ppt/ /quiz/ PBL/ Videos/ Animatio				
		1.2		ebychev-Grübler-K		T1, R1	1					
		1.3		conditions for 4-1	bar chain	T1, R1	1					
		1.4	4 bar Mechai inversions.	nisms and its first an	d second	T1, R1	1					
		1.5	The Control of the Co	urth inversions of 4	bar mechanism	T1, R1	1					
1		1.6	Single slider first 2 invers	crank chain mechan ions	isms and their	T1, R1	1					
**		1.7	Third and for mechanism	urth inversions of sli	der crank chain	T1, R1	1:					
		1.8		ns with Lower Pa Exact Straight-Li		T1, R1	2					
		1.9	The second state of the se	Hart and Scott Russe		T1, R1	1					
		1.10	Approximate Grasshopper,	Straight-Line Mech , Watt, Tchebicheff a Mechanical advanta	anisms – and Robert	T1, R1	1					
		1.11		ott Russell mechanis	m, Hooke's	T1, R1	1					
Content beyond Syllabus			Linkage 3.10 s	software for motion ge mechanisms	neration of various		10					
					7	Total		14				
II §				Unit-2. Plane ar	nd motion anal	veis						

			of simple mechanisms			and talk	
		2.2	graphical velocity analysis using instantaneous centers	T1	2	/ppt/ /quiz/	
		2.3	velocity and acceleration analysis using loop closure equations	T1	2	Videos/ Animat	
	1	2.4	kinematic analysis of simple mechanisms	T1	1	on	
		2.5	slider crank mechanism dynamics	T1	1	0	
		2.6	Coincident points and Coriolis component of acceleration.	T1	2		
		2.7	Problems	TI	2		
Content beyond Syllabus			Determination of velocity and acceleration by using software		1		
D J I Harris				Total		13	
			Unit-3. Gyroscope & Gear Pro	file			
	for r and r pairs ins	3.1	Introduction to Gyroscope, Principle of gyroscope and terminology	R1,T1	1		
	e Cams for follower au of higher pa gear trains	3.2	gyroscopic effect in an aeroplane	T1, T2	1		
	S 15 5 5	3.3	gyroscopic effect in an ship, car	T1, T2	1	1	
	of the first of th	3.4	gyroscopic effect in an two wheeler	T1, T2	2	Chalk	
Ш	naty n an tior	3.5	Problems on gyroscope	T1, T2	2	and tal /ppt/ /quiz/ PBL/ Videos Anima	
	Design and analyze Cams for specified motion and follower and and analyze motion of higher pairs like toothed gears, gear trains	3.6	Gear parameters, fundamental law of gearing, Involute and cycloidal gear profiles	R1,T1	2		
		3.7	conjugate action, spur gear contact ratio	T1, T2	1		
		3.8	interference/undercutting	T1, T2	1		
		3.9	helical, bevel, worm, rack & pinion gears,	T1, T2	1		
	o, es	3.10	epicyclic and regular gear train kinematics.	R1,T1	2	on	
Content beyond Syllabus			Modeling of gyroscope		1		
				Total		15	
	200		Unit-4. Balancing of Rotating masses	s & Cams		av.	
	Analyze the effect of gyroscopic couple on planes and ships as well as Construction of turning moment diagrams and apply them in designing flywheels	4.1	Need for balancing, balancing of single mass using analytical and graphical methods	T1, T2	ì	Chalk	
		4.2	balancing of several masses in different planes, using analytical and graphical methods	T1, T2	2	and tall	
IV		# 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	4.3	Classification of cams and followers	T1, T2	1	/quiz/
		4.4	Terminology and definitions	T1, T2	1	Videos/	
		4.5	Displacement diagrams, Uniform velocity, parabolic, simple harmonic and cycloidal motions	T1, T2	2	Animat on/flips	
		4.6	specified contour cams- circular and tangent cams	T1, T2	2	ed class	
	< 33 88	4.7	pressure angle and undercutting	T1, T2	1	1	
Content beyond Syllabus			uto CAD software for generating cam profiles		1		
Thaous				Total		11	
	2 - 1	τ	nit 5. Vibrations & Turning Moment Diagra		ywhe		
v	ers and recipr ocatin	5.1	Introduction, degree of freedom, types of vibrations	T1, R1	1	Chalk	

	5.2	free natural vibrations, Newton method and energy method for single degree of freedom	T1, R1	2	and talk /ppt/
7	5,3	Damped vibrations- under damped	T1, R1	-1	/quiz/
4	5.4	critically damped and over damped systems	T1, R1	1	PBL/
	5.5	forced vibrations with and without damping in single degree of freedom	T1, R1	2	Videos/ Animati
	5.6	Vibration isolation and transmissibility	T1, R1	1	on
	5.7	Turning moment diagrams for steam engine	Tl, Rl	1	-
	5.8	I.C engine and Multi Cylinder Engine.	T1, R1	1	
	5.9	Crank effort - coefficient of fluctuation of energy	T1, R1	1	
	5.10	Fly Wheel and their design, fly wheels for punching press.	T1, R1	2	
Content beyond Syllabus	Mo	1			
Sylmous			Total		14
		CUMULATIVE PROPOSED P	ERIODS		67
Text Bo	ooks:				
S.No.	AUTHORS, BOOK	TITLE, EDITION, PUBLISHER, YEAR OF 1	PUBLICAT	TON	
1	S. S. Rattan, Theory of Machines, fifth edition, TMH, 2019				
2	R.K. Bansal, J.S. Brar Theory of Machines, fifth edition, Laxmi Publications (P)Ltd, 2016				
Referen	ice Books:	55.W. = 5 +		2012.02	
S.No.	AUTHORS, BOOK	TITLE, EDITION, PUBLISHER, YEAR OF 1	PUBLICAT	TON	
1	R S Khurmi J K Gunta Theory of Machines, 15 edition, S. Chand, 2012				
2	V.P. Singh, Theory of M	achines,6 edition ,Dhanpat Rai & Co. (P) Limited,201	7		
Web D	etails				
1	http://mechanicalex	pressions.com/explore/kinematics			
	http://vlabs.iitkgp.ernet.in/mr				
2	http://vlabs.iitkgp.er	net.in/mr			

		Name	Signature with Date
i.	Faculty	Mr. B MAHESH KRISHNA	Ballh
ii.	Faculty II (for common Course)	Mr. V RAMBABU	V. Landely
iii.	Course Coordinator	Mr. B MAHESH KRISHNA	Balling
iv.	Module Coordinator	Dr.M FRANCIS LUTHER KING	16h - 45
v.	Programme Coordinator	Dr.M FRANCIS LUTHER KING	We -



Principal