

SWARNANDHRA COLLEGE OF ENGINEERING AND TECHNOLOGY

(Autonomous)

Narsapur, West Godavari District, A.P. 534280

DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING

TEACHING PLAN

Course Cour Code Title			Semester	Branch	Conta Period /Weel	ls Acadel		Date of commencement of Semester	
20CS6E04 AI Too Techniqu Applica		es and	B.Tech / VI	CSE	5	2024-20	025	18-11-2024	
COL	JRSE C	UTCOME	S						
1	CO1: O	bserve buil	d intellie	gent agents f	or search and	games(K2)		
2	CO1: Observe build intelligent agents for search and games(K2)								
	CO2: Construct AI problems through Python/Prolog/etc(K3)								
3	CO3: Illustrate learning optimization and inference algorithms for model learning(K4)							(K4)	
4	CO4: Develop programs for an agent to learn and act in a structured environment. (K3)							t. (K3)	
5				MDP conce	N N				
Unit	Ou	t Comes / om's Level	Topics No.	,	opics/Activity		Text Book / Reference	Con act Hou	Method
				UNI	Γ-I: Introdu	etion	200000000		
		CO1: Observe build intelligent agents for search and games(K2)		Concept of			T1	1	Chalk & talk
				history			T1	1	PPT
				current sta	itus		T1	1	PPT
	604			Scope of A	ΑI		T1	1	PPT
				Agents		5. %	T1	1	PPT
				Environm	ents		T1,R1	1_	PPT
I	ager			Problem I	Cormulations	=	T1,R1	1	Flipped Learning
				Review of structures	tree and grap	h	T1,R1	1	Chalk & talk
				Examples	of tree and gr	aph	T1,R1	1	PPT
				State space	e representati	on	T1,R1	1	PPT
				Search graph and Search tree.		T1,R1	1	PPT	
			1.9.1	Examples			T1,R1	1	PPT
							Total		13
				UNIT-II	: Search A	lgorithms	i.		
	CO2:		2.1	Random		0	T1,R1	1	PPT
		struct AI	2.2	Search w	ith closed and	open list	T1,R1	1	PPT
II		olems	2.3	Depth fir		***************************************	T1,R1	1	Experimental Learning
	124004071ACA	on/Prolo	2.4	Breadth 1	first search		T1,R1	1	PPT



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	g/etc(K3)	2.5		Heuristic search		T1,R1	1	Chalk & talk
	8,000(1.0)	2.5.			T1,R1	1	PPT	
		2.6	2.6 Best first search			T1,R1	1	PPT
		2.7	,	A* algorithm		T1,R1	1	PPT
		2.8		Game Search		T1,R1	1	PPT
		2.8.1		Minimax Algorithm		T1,R1	1	PPT
		2.8.		Alpha beta pruning		T1,R1	1	PPT
				Total				13
			UN	IIT-III: Probabilistic R	Reasoni			
	CO3:	3.1	Prob	pability		T1,R1	1	Chalk & talk
	Illustrate learning optimization and	3.2	Con	ditional probability		T1,R1	1	PPT
		3.3	Bayes Rule			T1,R1	1	Chalk & talk
		3.4	Bay	esian Networks		T1,R1	1	PPT
***		3.4.1	Exa	mple Bayesian network		T1,R1	1	PPT
III		3.5		struction and inference		T1,R1	1	PPT
	inference	3.5.1	Exa	mple on construction and infer	ence	T1,R1	1	PPT
	algorithms	3.6		poral model		T1,R1	1	PPT
	for model	3.6.1				T1,R1	1	PPT
	learning(K4)	3.7		len Markov model		T1,R1	1	PPT
		3.7.1	Exa	mple hidden markov decision r	nodel	T1,R1	1	Quiz
	Content beyond		Dvr	namic Bayesian Networks			1	Flipped Learning
			- ,.	CONTROL CONTRO				
	Syllabus		- 3.	V		Tota		12
				NIT-IV: Markov Decision	ı proce			
		4.1	U					
		4.1	U)	NIT-IV: Markov Decision IDP formulation	T1	SS	ıl	12
	Syllabus CO4: Develop programs for		M ut	NIT-IV: Markov Decision IDP formulation illity theory	T1 T1	ss ,R1	1	12 PPT
	CO4: Develop programs for an agent to	4.2	U M	NIT-IV: Markov Decision IDP formulation iility theory tility functions	T1 T1 T1	,R1 ,R1	1 1	12 PPT PPT
IV	CO4: Develop programs for an agent to learn and act	4.2 4.3 4.3.1	U) M ut U	NIT-IV: Markov Decision IDP formulation Collision theory	T1 T1 T1 T1	,R1 ,R1 ,R1	1 1 1	PPT PPT PPT
IV	CO4: Develop programs for an agent to learn and act in a structured	4.2	U) M ut U ut ve	NIT-IV: Markov Decision IDP formulation iility theory tility functions	T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1	PPT PPT PPT PPT
IV	CO4: Develop programs for an agent to learn and act in a structured environment.	4.2 4.3 4.3.1 4.4 4.4.1	U) M ut U ut ve	NIT-IV: Markov Decision IDP formulation Callity theory Itility functions Callity functions examples Callue iteration Examples	T1 T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative
IV	CO4: Develop programs for an agent to learn and act in a structured	4.2 4.3 4.3.1 4.4 4.4.1 4.5	U) M ut U ut ve	NIT-IV: Markov Decision IDP formulation Cility theory Itility functions Cility functions examples Calculate iteration Examples Colicyiteration	T1 T1 T1 T1 T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning
IV	CO4: Develop programs for an agent to learn and act in a structured environment.	4.2 4.3 4.3.1 4.4 4.4.1 4.5 4.6	UI Mut U ut va E:	NIT-IV: Markov Decision IDP formulation Callity theory Callity functions Callity functions examples Callue iteration Examples Colicyiteration Cartially observable MDPs	T1 T1 T1 T1 T1 T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT
IV	CO4: Develop programs for an agent to learn and act in a structured environment.	4.2 4.3 4.3.1 4.4 4.4.1 4.5	UI Mut U ut va E:	NIT-IV: Markov Decision IDP formulation Cility theory Itility functions Cility functions examples Calculate iteration Examples Colicyiteration	T1 T1 T1 T1 T1 T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT Chalk & talk
IV	CO4: Develop programs for an agent to learn and act in a structured environment.	4.2 4.3 4.3.1 4.4 4.4.1 4.5 4.6	UI Mut U ut va E:	NIT-IV: Markov Decision IDP formulation Callity theory Callity functions Callity functions examples Callue iteration Examples Colicyiteration Cartially observable MDPs	T1 T1 T1 T1 T1 T1 T1 T1 T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT Chalk & talk PPT
IV	CO4: Develop programs for an agent to learn and act in a structured environment. (K3)	4.2 4.3 4.3.1 4.4 4.4.1 4.5 4.6	UI Mut U ut va E:	NIT-IV: Markov Decision IDP formulation Cility theory Itility functions Cility functions Cility functions examples Calculate iteration Examples Colicyiteration Cartially observable MDPs IDP concept examples	T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT Chalk & talk PPT
	CO4: Develop programs for an agent to learn and act in a structured environment. (K3)	4.2 4.3 4.3.1 4.4 4.4.1 4.5 4.6 4.6.1	UI M ut U ut va E:	NIT-IV: Markov Decision IDP formulation Cility theory Itility functions Cility functions Cility functions examples Callue iteration Cartially observable MDPs IDP concept examples CINIT-V: Reinforcement L Cassive reinforcement Carting	T1	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT Chalk & talk PPT 11
IV	CO4: Develop programs for an agent to learn and act in a structured environment. (K3)	4.2 4.3 4.3.1 4.4 4.4.1 4.5 4.6 4.6.1	UI Mut U ut ve E:	NIT-IV: Markov Decision (DP formulation (ility theory tility functions iility functions examples alue iteration (xamples (blicyiteration (artially observable MDPs (IDP concept examples (INIT-V: Reinforcement Leassive reinforcement	T1 T	,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1 ,R1	1 1 1 1 1 1 1	PPT PPT PPT PPT PPT Collaborative Learning PPT Chalk & talk PPT 11 Chalk & talk



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		programming						
	5.4	temporal difference learning	T1,R1	1	PPT			
	5.5	Passive reinforcement learning	T1,R1	1	PPT			
	5.5	active reinforcement learning	T1,R1	1	Active Learning			
	5.6	Q learning	T1,R1	1	PPT			
	5.6.1	Q learning examples	T1,R1	1	PPT			
			11					
		CUMULATIVE PROPOSE	D PERIODS		60			
Text B	A-1203 O(1) 48(UR)		311-23					
S.No.	AUTHORS, BOOK TITLE, EDITION, PUBLISHER, YEAR OF PUBLICATION							
1	Stuart Russell, Peter Norvig, "Artificial Intelligence - A Modern Approach", 3rd Edition, Pearson							
	Education / Prentice Hall of India, 2010.							
2	Elaine Rich and Kevin Knight, "Artificial Intelligence", 3rd Edition, Tata McGraw Hill. 2017.							
Refere	Reference Books:							
S.No.	AUTHORS, BOOK TITLE, EDITION, PUBLISHER, YEAR OF PUBLICATION							
1	Nils J. Nilsson, "Artificial Intelligence: A new Synthesis", Harcourt Asia Pvt. Ltd., 2000.							
2	Trivedi, M.C., "A Classical Approach to Artifical Intelligence", 2nd edition, Khanna Book Publishing, 2018							
3	Prateek Joshi, "Artificial Intelligence with Python", Packt Publishing, 2017.							
Web Details								
1	https://www.pdfdrive.net/artificial-intelligence-a-modern-approach-3rd-edition-							
	e32618455.html							
2	https://www.coursera.org/learn/introduction-to-ai							
		12.0	~.					

		Name	Signature with Date
i.	Faculty I	Mr.P.SRINU VASARAO	Pamuel
ii.	Faculty II	Dr.T.Murali mohan	1.4
iii.	Faculty III	Mr.N.Tulasi Raju	NOW
iv.	Faculty IV	Mrs.K.Sirisha	KLil
v.	Course Coordinator	Mr.P.Srinu Vasarao	P Sonze
vi.	Module Coordinator	Dr.T.Murali mohan	0.40
vii.	Programme Coordinator	Dr.P.Srinivasulu	(M)

HOD

Principal